

Diagonalizable operators  
Math 130 Linear Algebra  
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Some linear operators  $T : V \rightarrow V$  have the nice property that there is some basis for  $V$  so that the matrix representing  $T$  is a diagonal matrix. We'll call those operators *diagonalizable operators*. We'll call a square matrix  $A$  a *diagonalizable matrix* if it is conjugate to a diagonal matrix, that is, there exists an invertible matrix  $P$  so that  $P^{-1}AP$  is a diagonal matrix. That's the same as saying that under a change of basis,  $A$  becomes a diagonal matrix.

Reflections are examples of diagonalizable operators as are rotations if  $\mathbf{C}$  is your field of scalars.

Not all linear operators are diagonalizable. The simplest one is  $\mathbf{R}^2 \rightarrow \mathbf{R}^2$ ,  $(x, y) \rightarrow (y, 0)$  whose matrix is  $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ . No conjugate of it is diagonal. It's an example of a *nilpotent* matrix, since some power of it, namely  $A^2$ , is the 0-matrix. In general, nilpotent matrices aren't diagonalizable. There are many other matrices that aren't diagonalizable as well.

**Theorem 1.** A linear operator on an  $n$ -dimensional vector space is diagonalizable if and only if it has a basis of  $n$  eigenvectors, in which case the diagonal entries are the eigenvalues for those eigenvectors.

*Proof.* If it's diagonalizable, then there's a basis for which the matrix representing it is diagonal. The transformation therefore acts on the  $i^{\text{th}}$  basis vector by multiplying it by the  $i^{\text{th}}$  diagonal entry, so it's an eigenvector. Thus, all the vectors in that basis are eigenvectors for their associated diagonal entries.

Conversely, if you have a basis of  $n$  eigenvectors, then the matrix representing the transformation is diagonal since each eigenvector is multiplied by its associated eigenvalue. Q.E.D.

We'll see soon that if a linear operator on an  $n$ -dimensional space has  $n$  distinct eigenvalues, then it's diagonalizable. But first, a preliminary theorem.

**Theorem 2.** Eigenvectors that are associated to distinct eigenvalues are independent. That is, if  $\lambda_1, \lambda_2, \dots, \lambda_k$  are different eigenvalues of an operator  $T$ , and an eigenvector  $\mathbf{v}_i$  is associated to each eigenvalue  $\lambda_i$ , then the set of vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$  is linearly independent.

*Proof.* Assume by induction that the first  $k - 1$  of the eigenvectors are independent. We'll show all  $k$  of them are. Suppose some linear combination of all  $k$  of them equals  $\mathbf{0}$ :

$$c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_k\mathbf{v}_k = \mathbf{0}.$$

Take  $T - \lambda_k I$  of both sides of that equation. The left side simplifies

$$\begin{aligned} & (T - \lambda_k I)(c_1\mathbf{v}_1 + \dots + c_k\mathbf{v}_k) \\ &= c_1T(\mathbf{v}_1) - \lambda_k c_1\mathbf{v}_1 + \dots + c_kT(\mathbf{v}_k) - \lambda_k c_k\mathbf{v}_k \\ &= c_1(\lambda_1 - \lambda_k)\mathbf{v}_1 + \dots + c_k(\lambda_k - \lambda_k)\mathbf{v}_k \\ &= c_1(\lambda_1 - \lambda_k)\mathbf{v}_1 + \dots + c_{k-1}(\lambda_{k-1} - \lambda_k)\mathbf{v}_{k-1} \end{aligned}$$

and, of course, the right side is  $\mathbf{0}$ . That gives us a linear combination of the first  $k - 1$  vectors which equals  $\mathbf{0}$ , so all their coefficients are 0:

$$c_1(\lambda_1 - \lambda_k) = \dots = c_{k-1}(\lambda_{k-1} - \lambda_k) = 0$$

Since  $\lambda_k$  does not equal any of the other  $\lambda_i$ 's, therefore all the  $c_i$ 's are 0:

$$c_1 = \dots = c_{k-1} = 0$$

The original equation now says  $c_k\mathbf{v}_k = \mathbf{0}$ , and since the eigenvector  $\mathbf{v}_k$  is not 0, therefore  $c_k = 0$ . Thus all  $k$  eigenvectors are linearly independent. Q.E.D.

**Corollary 3.** If a linear operator on an  $n$ -dimensional vector space has  $n$  distinct eigenvalues, then it's diagonalizable.

*Proof.* Take an eigenvector for each eigenvalue. By the preceding theorem, they're independent, and since there are  $n$  of them, they form a basis of the  $n$ -dimensional vector space. The matrix representing the transformation with respect to this basis is diagonal and has the eigenvalues displayed down the diagonal. Q.E.D.

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